

ENGINEERING CHANGE NOTIFICATION FORM

ECN: 100-001-000122		REV: 1	ISSUE DATE: 12/18/2012								
TYPE OF CHANGE: Firmware Modification											
DETAILED DESCRIPTION OF CHANGE: Firmware improvements outlined in detail below.											
REASON FOR CHANGE: Functionality Improvements and bug fixes.											
PRODUCTS AFFECTED: <table border="1"> <thead> <tr> <th>Firmware Version</th> <th>Model</th> </tr> </thead> <tbody> <tr> <td rowspan="5">Units with firmware version 2.38 and earlier</td> <td>FireFly-1C</td> </tr> <tr> <td>FireFly-II</td> </tr> <tr> <td>FireFly-IIA (and ULN-xxxx)</td> </tr> <tr> <td>LC_1x1</td> </tr> <tr> <td>Mini-JLT</td> </tr> </tbody> </table>				Firmware Version	Model	Units with firmware version 2.38 and earlier	FireFly-1C	FireFly-II	FireFly-IIA (and ULN-xxxx)	LC_1x1	Mini-JLT
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Issue 1): <p>continuing regression-testing of firmware 2.38 on non-timing receiver products in moving vehicles showed that firmware release 2.38 may cause the GPS unit to stay in Position Hold mode independently of the GPS:DYNAMIC settings and vehicle velocity. Not all units are affected; units that are not affected by this issue do not need to be updated. This issue can be verified by checking the SYST:STAT? command output to say "Position Hold" instead of the expected "3D Fix" indication. If the unit indicates "3D Fix" in the syst:stat? command the unit is not affected and does not need to be updated.</p> <p>Units that are affected will permanently keep the GPS receiver in stationary mode, and this may cause the GPS receiver to lose lock and to stop generating a PVT solution at speeds in excess of ~40mph. Applications that are stationary and do not move the GPS antenna are not affected and do not need the firmware update.</p> <p>Cause: A residual timing-receiver related EEPROM setting may have been incorrectly set to "timing mode enabled" at the factory, even though GPS receivers that are not timing-receivers do not support this feature. The side effect of this EEPROM setting is that the GPS:Dynamic mode only operates in stationary mode. This EEPROM setting cannot be changed in the field.</p> <p>Solution: Upgrading affected units to firmware revision 2.39 will fix this issue.</p>											
Issue 2): <p>NMEA sentences such as \$GPGGA may be missing a leading zero in the longitude output for longitudes less than +/-10 degrees. Longitudes greater or equal to +/-10 degrees are not affected. NMEA specifies a constant number of digits for longitude, and the missing leading zero may cause some application software to interpret the longitude incorrectly. The latitude output is properly formatted.</p> <p>Cause: The NMEA output format is incorrectly programmed by missing a leading zero in the longitude field for longitudes less than 10 degrees from Greenwich.</p>											

Solution:

Upgrading affected units to firmware revision 2.39 will fix this issue.

REFERENCE DOCUMENTS/ATTACHMENTS:

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PLEASE CONTACT JACKSON LABS TECHNOLOGIES, INC. WITH ANY QUESTIONS